Drive Concept for SIMATIC MICRO-DRIVE

ebmpapst

Product Catalog 2019-04

the engineer's choice



About ebm-papst

We believe the consistent further development of our highly-efficient GreenTech EC technology provides our customers with the best opportunities



the engineer's choice

Six reasons that make us the ideal partner:

Our systems expertise.

You want the best solution for every project. The entire ventilation system must thus be considered as a whole. And that's what we do – with motor technology that sets standards, sophisticated electronics and aerodynamic designs – all from a single source and perfectly matched.

Our spirit of invention.

We are also always able to develop customized solutions for you with our versatile team of over 600 engineers and technicians.

Our lead in technology.

We are not only pioneers and trailblazers in the development of highly efficient EC technology, we also recognized the opportunities of digitization at an early stage. Therefore, we can offer solutions today that combine the highest energy efficiency with the advantages of IoT and digital networking.

Closeness to our customers.

ebm-papst has 25 production locations worldwide (including facilities in Germany, China and the USA), together with 49 sales offices, each of which has a dense network of sales representatives. You will always have a local contact, someone who speaks your language and knows your market.

Our standard of quality.

Our quality management is uncompromising, at every step in every process. This is underscored by our certification according to international standards including DIN EN ISO 9001, TS declaration of conformity and DIN EN ISO 14001.

Our sustainable approach.

Assuming responsibility for the environment, for our employees and for society is an integral part of our corporate philosophy. We develop products with an eye to maximum environmental compatibility, in particular resource-preserving production methods. We promote environmental awareness among our young staff and are actively involved in sports, culture and education. That's what makes us a leading company – and an ideal partner for you.

Drive Concept for SIMATIC MICRO-DRIVE



the engineer's choice

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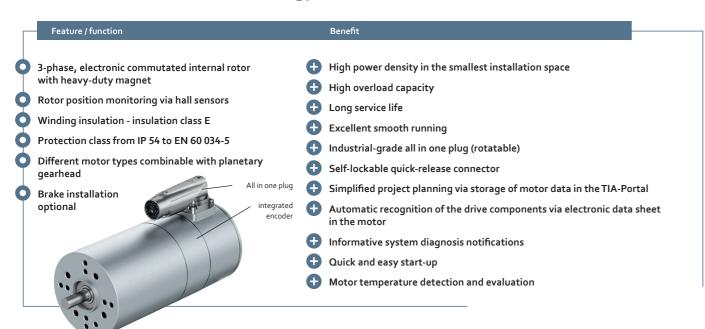
SIMATIC MICRO-DRIVE is the new servo drive system in the safety extra-low voltage range. Consisting of the ProfiDriveControl (PDC) servo controller and flexibly usable motors and connecting cables.

Therefore ebm-papst offers motors and gearheads in different construction sizes within a product partner program.

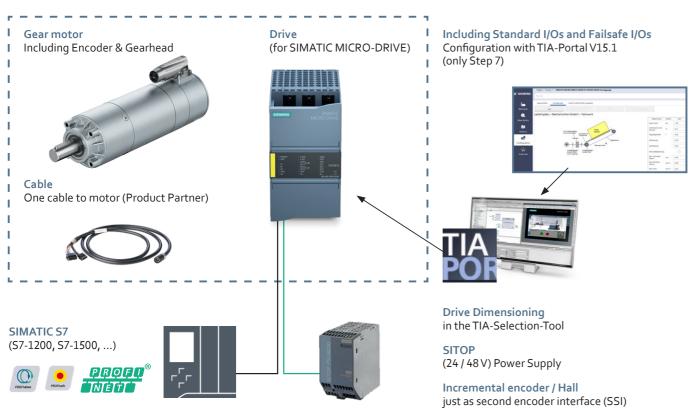
| Brushless internal rotor motors E | CI | ECI-42.20-K1 | ECI-42.40-K1 | ECI-63.20-K1 | ECI-63.40-K1 | ECI-63.60-K1 |
|-----------------------------------|-----|--------------|--------------|--------------|--------------|--------------|
| LINI | VDC | 24 | 24 | 24 | 24 | 24 |
| UN VD | VDC | 48 | 48 | 48 | 48 | 48 |
| MN | mNm | | | | | |
| | W | | | | | |
| nΝ | rpm | | | | | |
| | mm | | | | | |
| d | mm | | | | | |
| Motor Feedback | | | | | | |
| K1 (Hall sensor system) | | Χ | X | X | X | X |
| Siemens iQ-Encoder | | Χ | X | X | X | X |
| Brakes | | | | | | |
| Hold brake (quiescent current) | | Χ | X | X | Χ | X |
| Gearheads | | | | | | |
| PerfomaxPlus 42.1 | | Χ | X | | | |
| PerfomaxPlus 42.2 | | | | X | Χ | X |
| PerfomaxPlus 63.1 | | | | X | Χ | X |
| PerfomaxPlus 63.2 | | | | X | Χ | X |
| PDC (ProfiDriveControl) | | | | | | |
| PDC 50 / 50F / 50FIO | | Χ | | | | |
| PDC 100 / 100F / 100FIO | | | X | | | |
| PDC 200 / 200F / 200FIO | | | | Χ | X | |
| PDC 400 / 400F / 400FIO | | | | | | X |

Information / Advantages SIMATIC MICRO-DRIVE

ECI-Motor with iQ-Encoder Technology



System Overview SIMATIC MICRO-DRIVE



SIMATIC MICRO-DRIVE

| | Feature / function | | Benefit | |
|------------|---|-------|---|--|
| 000 000000 | Flexibility & combinability of system components PROFINET IRT (1 ms) Safety Integrated: STO, SS1, SLT, SLS, SBC, SSM via PROFIsafe TIA Portal integration "One Button Tuning" One cable to motor Integrated C1 EMC-Filter 24-48 V: 0,05-1 kW Battery supply incl. energy recovery UL & Marine certification | 0 0 0 | Universally applicable Increased performance Fulfills high demands for safety Easy engineering Saves time on installation Ready for various markets | SIEMENS SIMATIC MICRO-DRIVE SIEMENS SIMATIC MICRO-DRIVE STATE ST |

Information / Advantages through connection to SIMATIC S7-1500 @ SINAMICS in TIA portal

| Feature / function | Benefit |
|--|--|
| Efficient Engineering | Shorter training time |
| One single uniform engineering platform | Reduced engineering effort |
| Common functionalities (trace, library, etc.) | Automatic consistency within the project |
| ntegrated Drive Control | |
| SIMATIC Motion Control technology objects | Drives can be easily connected to SIMATIC PLCs |
| Drive libraries | Motion control applications quickly and simply realized |
| Safety Integrated | |
| Efficient safety commissioning | Installation and commissioning even faster |
| Standard components with integrated safety technology | Less hardware / No additional components |
| ntegrated communication function block for SINAMICS Safety | Greater flexibility for extensions and adaptations |
| PROFINET | |
| PROFIdrive | Standardized communication based on standard Ethernet |
| PROFIsafe | Easy Remote-Access |
| ntegrated System Diagnostics | System messages are available without any engineering effort (TIA Portal, PLC, Web-Server & HMI) |

ECI-Motor ECI-42.XX-K1



www.ebmpapst.com/eci-motoren

Description

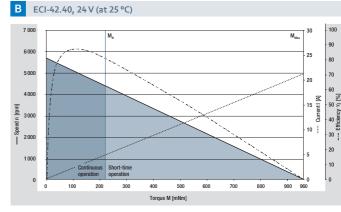
- Highly dynamic 3-phase internal rotor motor with EC technology
- Low cogging torque
- Robust, noise-optimized ball bearing system for a long service life
- High efficiency and high power density realized in a compact design
- Basic motor with electronic module K1 for operation with external control electronics
- Mechanical design and interfaces designed for modular flexibility
- Protection class IP 54 and connection by connector system

| Туре | | ECI-42.20-K1-B00 | ECI-42.20-K1-D00 | ECI-42.40-K1-B00 | ECI-42.40-K1-D00 |
|--|------------|-----------------------|-----------------------|-------------------------|-------------------|
| Characteristic curve | | A | | В | |
| Nominal voltage (U _N) | V DC | 24 | 48 | 24 | 48 |
| Nominal speed (n _N) ²⁾ | rpm | 4 000 | 4 000 | 4 000 | 4 000 |
| Nominal torque (M _N) ²⁾ | mNm | 110 | 110 | 220 | 220 |
| Nominal current (I _N) ²⁾ | А | 2.50 | 1.30 | 5.10 | 2.60 |
| Nominal output power (P _N) ²⁾ | W | 46.0 | 46.0 | 92.0 | 92.0 |
| Starting torque (M _{max}) | mNm | 480 | 480 | 960 | 960 |
| Permissible peak current (I _{max}) ³⁾ | Α | 7.50 | 3.90 | 15.3 | 7.80 |
| Speed at no-load operation (n _L) | rpm | 5 900 | 5 900 | 5 700 | 5 700 |
| No-load current (I _L) | А | 0.33 | 0.10 | 0.40 | 0.20 |
| Permanent stall torque (M _{NO}) | mNm | 100 | 100 | 200 | 200 |
| Recommended speed control range | rpm | 0 5 000 | 0 5 000 | 0 5 000 | 0 5 000 |
| Rotor moment of inertia (J _R) | kgm² x10-6 | 3.42 | 3.42 | 6.70 | 6.70 |
| Motor constant (K _E) | mVs/rad | 35.2 | 84.2 | 42.8 | 83.9 |
| Connection resistance (R _v) | Ω | 0.85 | 3.20 | 0.39 | 1.50 |
| Connection inductance (L _q) | mH | 1.45 | 5.91 | 0.64 | 2.79 |
| Connection inductance (L _d) | mH | 0.81 | 3.37 | 0.37 | 1.56 |
| Overload protection | | | To be implemented via | the control electronics | |
| Permissible ambient temperature range (T _U) | °C | 0 +40 | 0 +40 | 0 +40 | 0 +40 |
| Part number | | SSE4220BK1xxxxxxxxx60 | SSE4220DK1xxxxxxxx60 | SSE4240BK1xxxxxxxxx60 | SSE4240DK1xxxxxxx |

 $^{1)}$ The degree of protection refers to the installed condition with sealing on the flange side $^{2)}$ At TU max. 40 $^{\circ}$ C $^{3)}$ Permissible maximum current duration: max. 3 seconds – can be repeated after complete cool down

Preliminary data, subject to alterations

A ECI-42.20, 24 V (at 25 °C) 250 300 350 400 450 480



Characteristic curve 48 V on request

Characteristic curve 48 V on request

Modular construction kit



Basic motor Planetary gearheads Performax®Plus 42 from page 14

Encoder system magnetic incremental iQ-Encoder

PDC controller PDC 50 PDC100



| | # | |
|--------|---------|------|
| page 5 | SIEMENS | |
| page 5 | | |
| | iš. | hib. |
| | | |

| Cable | | |
|------------------|-------|--------|
| | PDC50 | PDC100 |
| Connection cable | LA02 | LA02 |
| Brake cable | LPBr2 | LPBr2 |
| | | |

(Produkte & Services -> Antriebstechnik -> Umrichter -> Servoantriebssystem SIMATIC MCRO-DRIVE)

Available from KnorrTec More at: https://www.knorrtec.de (Unternehmen -> Kooperation)

Available from Siemens More at: https://new.siemens.com

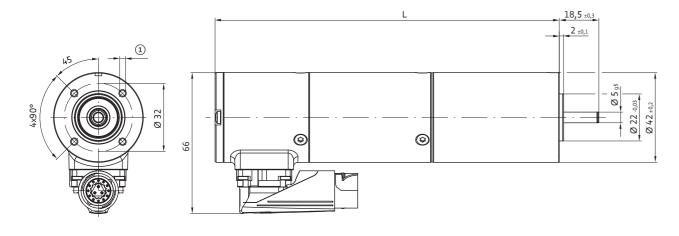


For motor-gearbox combinations, depending on the choice of the single components, the maximum allowable torque (gearbox) can be exceeded or respectively not reached.

All dimensions in mm

Technical drawing without brake

All dimensions in mm



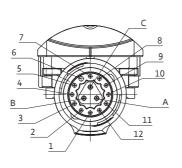
 $\textcircled{1} \ \, \overset{\text{4 x for thread-forming screws M3 according to DIN 7500,}}{\text{screw-in depth max. 9.5}}$



Permissible shaft load

Electrical connection without brake

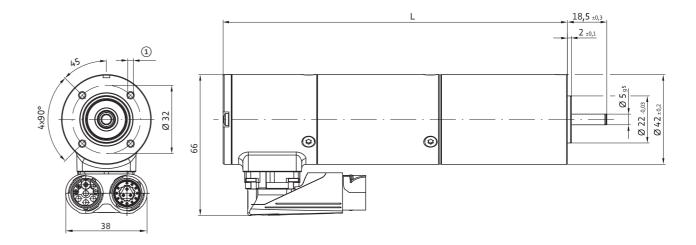
| | Pin | Configuration | Function |
|---------|------------|---------------|----------------------------|
| | 1 | HA | Hall signal A |
| | 2 | НВ | Hall signal B |
| HALL | 3 | НC | Hall signal C |
| | 4 | +12V | Supply voltage |
| 5 | | GND | Ground |
| | 6 | empty | empty |
| | 7 | А | Encoder channel A |
| | 8 | /A | Encoder channel A inverted |
| - 1 | 9 | В | Encoder channel B |
| Encoder | Encoder 10 | /B | Encoder channel B inverted |
| | 11 | +5V | Supply voltage |
| | 12 | GND | Ground |
| | Α | U | Winding connector U |
| Motor | В | V | Winding connector V |
| | С | W | Winding connector W |
| | | | |



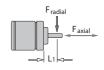
Technical drawing with integrated brake

Type L ECI-42.20 191 ± 0.4

ECI-42.20 191 ± 0.4 ECI-42.40 211 ± 0.4



 $\textcircled{1} \ \, \frac{\text{4 x for thread-forming screws M3 according to DIN 7500,}}{\text{screw-in depth max. 9.5}}$

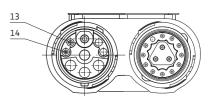


Permissible shaft load

axial: 30 N Permissible simultaneous shaft loads at rated speed and service life expectancy L10 (in rated operation) from 20 000 h (at TU max. 40 °C)

Electrical connection with integrated brake

| | | Function |
|----------|-------|----------------|
| Brake 13 | +24 V | Supply voltage |
| 14 | GND | Ground |



ECI-Motor ECI-63.XX-K1



www.ebmpapst.com/eci-motoren

Description

- Highly dynamic 3-phase internal rotor motor with EC technology
- Low cogging torque
- Robust, noise-optimized ball bearing system for a long service life
- High efficiency and high power density realized in a compact design
- Basic motor with electronic module K1 for operation with external control electronics
- Mechanical design and interfaces designed for modular flexibility
- Protection class IP 54 and connection by connector system

| Туре | | ECI-63.20-K1 -B00 | ECI-63.20-K1 -D00 | ECI-63.40-K1 -B00 | ECI-63.40-K1 -D00 | ECI-63.60-K1 -D00 |
|--|------------|----------------------|----------------------|-----------------------|-----------------------|----------------------|
| Characteristic curve | | A | | В | | C |
| Nominal voltage (U _N) | V DC | 24 | 48 | 24 | 48 | 48 |
| Nominal speed (n _N) ²⁾ | rpm | 4 000 | 4 000 | 4 000 | 4 000 | 4 000 |
| Nominal torque (M _N) ²⁾ | mNm | 360 | 360 | 670 | 670 | 880 |
| Nominal current (I _N) ²⁾ | Α | 8.50 | 4.50 | 14.0 | 6.50 | 8.50 |
| Nominal output power (P _N) ²⁾ | W | 150 | 150 | 280 | 280 | 370 |
| Starting torque (M _{max}) | mNm | 1 800 | 1 800 | 3 300 | 3 300 | 4 400 |
| Permissible peak current (I _{max}) ³⁾ | Α | 25.5 | 13.5 | 42.0 | 19.5 | 25.5 |
| Speed at no-load operation (n _L) | rpm | 5 250 | 5 250 | 5 250 | 5 250 | 5 250 |
| No-load current (I _L) | Α | 0.50 | 0.30 | 0.70 | 0.32 | 0.45 |
| Recommended speed control range | rpm | 0 5 000 | 0 5 000 | 0 5 000 | 0 5 000 | 0 5 000 |
| Rotor moment of inertia (J _R) | kgm² x10-6 | 19.0 | 19.0 | 38.0 | 38.0 | 57.0 |
| Motor constant (K _E) | mVs/rad | 41.4 | 73.3 | 40.4 | 83.8 | 83.8 |
| Connection resistance (R _V) | Ω | 0.14 | 0.42 | 0.08 | 0.24 | 0.15 |
| Connection inductance (L _q) | mH | 0.33 | 1.12 | 0.16 | 0.65 | 0.38 |
| Connection inductance (L _d) | mH | 0.20 | 0.69 | 0.09 | 0.38 | 0.22 |
| Overload protection | | | To be imple | mented via the contro | l electronics | |
| Permissible ambient temperature range (T_U) | °C | 0 +40 | 0 +40 | 0 +40 | 0 +40 | 0 +40 |
| Part number | | SSE6320BK1xxxxxxxx60 | SSE6320DK1xxxxxxxx60 | SSE6340BK1xxxxxxxx60 | SSE6340DK1xxxxxxxxx60 | SSE6360DK1xxxxxxxx |

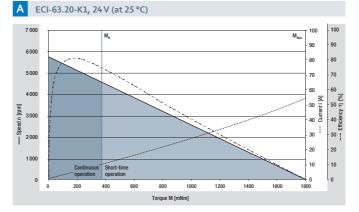
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1) The degree of protection refers to the installed condition with sealing on the flange side

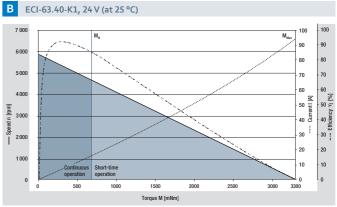
The shaft geometry in the IPS4 version is different from the displayed sketch ²⁾ At TU max. 40 °C

urrent duration: max. 3 seconds – can be repeated after complete cool down

Preliminary data, subject to alterations



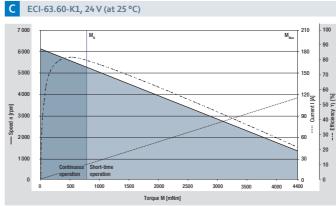
Characteristic curve 48 V on request



Planetary gearheads

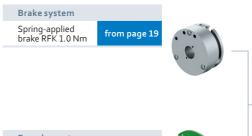
Performax®Plus 63 from page 16

Characteristic curve 48 V on request



Characteristic curve 48 V on request

Modular construction kit



Encoder system magnetic incremental iQ-Encoder

PDC controller PDC 200 PDC 400

Available from Siemens
More at: https://new.siemens.com
(Produkte & Services -> Antriebstechnik -> Umrichter ->
Servoantriebssystem SIMATIC MCRO-DRIVE)

| Cable | | |
|-------------------------|--------|--------|
| | PDC200 | PDC400 |
| Connection cable | LA02 | LA02 |
| Brake cable | LPBr2 | LPBr2 |
| Available from KnorrTec | | |

More at: https://www.knorrtec.de (Unternehmen -> Kooperation)

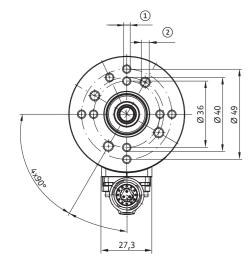


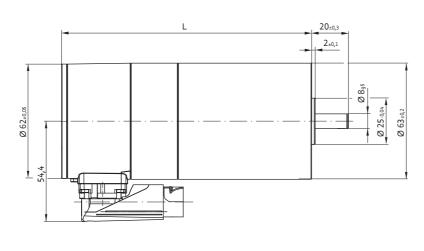
Basic motor

For motor-gearbox combinations, depending on the choice of the single components, the maximum allowable torque (gearbox) can be exceeded or respectively not reached.

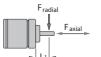
ebmpapst ebmpapst Drive Concept for SIMATIC MICRO-DRIVE · Edition 2019-04

All dimensions in mm





- 1 8 x for thread-forming screws M4 according to DIN 7500, screw-in depth max. 10
- 3 4 x for thread-forming screws M5 according to DIN 7500, screw-in depth max. 10

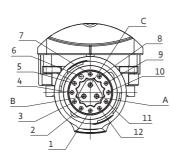


Permissible shaft load

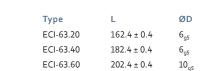
Permissible simultaneous shaft 150 N loads at rated speed and service life 150 N expectancy L10 (in rated operation) from 20 000 h (at TU max. 40 °C) 10 mm

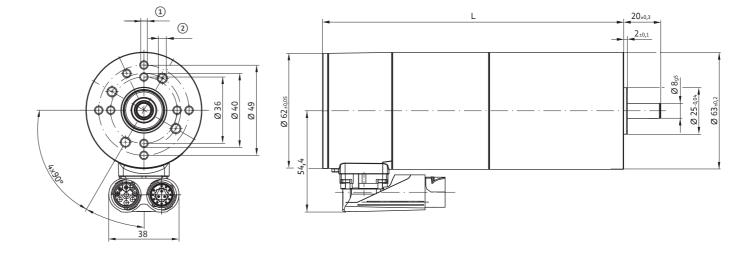
Electrical connection without brake

| 1 2 | ΗА | Hall signal A |
|-----|---|---|
| 2 | | rian signar A |
| 4 | НВ | Hall signal B |
| 3 | НC | Hall signal C |
| 4 | +12V | Supply voltage |
| 5 | GND | Ground |
| 6 | empty | empty |
| 7 | Α | Encoder channel A |
| 8 | /A | Encoder channel A inverted |
| 9 | В | Encoder channel B |
| 10 | /B | Encoder channel B inverted |
| 11 | +5V | Supply voltage |
| 12 | GND | Ground |
| Α | U | Winding connector U |
| В | V | Winding connector V |
| С | W | Winding connector W |
| | 4 5 6 7 8 9 10 11 11 12 A | 4 +12V 5 GND 6 empty 7 A 8 /A 9 B 10 /B 11 +5V 12 GND A U B V |



Technical drawing without brake





- $\textcircled{\scriptsize 1}$ 8 x for thread-forming screws M4 according to DIN 7500, screw-in depth max. 10
- 3 4 x for thread-forming screws M5 according to DIN 7500, screw-in depth max. 10



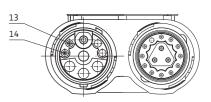
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Permissible shaft load

150 N Permissible simultaneous shaft loads at rated speed and service life 150 N expectancy L10 (in rated operation) from 20 000 h (at TU max. 40 °C) 10 mm

Electrical connection without brake

| | Pin | Configuration | Function |
|-------|-----|---------------|----------------|
| Brake | 13 | +24 V | Supply voltage |
| | 14 | GND | Ground |



Planetary gearhead Performax®Plus 42 for ECI-42.xx



www.ebmpapst.com/eci-motorer

Description

- High power density from compact
- Very quiet operation due to helical teeth in the first gear stage
- Planetary wheels made of plastic with op-timized sliding properties in the first stage ensure smooth operation
- Large effective diameter thanks to radial screw connection
- Efficient structure due to the use of many finished casting individual parts
- Arbitrary installation position permitted
- Maintenance-free grease lubrication for life

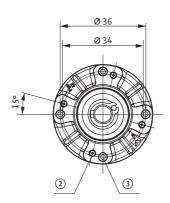
| Туре | | Performax | (®Plus 42.1 | Performax | ®Plus 42.2 |
|---|-----|-----------|-------------|-----------|------------|
| Reduction ratio | | 5.00 | 9.00 | 30.0 | 54.0 |
| No. of stages | | 1 | 1 | 2 | 2 |
| Efficiency | | 0.90 | 0.90 | 0.81 | 0.81 |
| Max. input speed (n ₁) | rpm | 6 000 | 6 000 | 6 000 | 6 000 |
| Rated output torque (M _{ab}) | Nm | 2.00 | 0.50 | 4.48 | 2.60 |
| Short-term torque (M_{max}) | Nm | 5.0 | 1.25 | 11.2 | 6.50 |
| Gear play | 0 | 0.7 1.2 | 0.7 1.2 | 0.7 1.2 | 0.7 1.2 |
| Permissible ambient temperature range (T_U) | °C | 0 +40 | 0 +40 | 0 +40 | 0 +40 |
| Operating mode | | S1 | S 1 | S1 | S1 |
| Protection class | | IP 50 | IP 50 | IP 50 | IP 50 |
| Weight | kg | 0.22 | 0.19 | 0.29 | 0.29 |
| Shaft load radial / axial | N | 250 / 150 | 250 / 150 | 250 / 150 | 250 / 150 |
| Service life | h | 5 000 | 5 000 | 5 000 | 5 000 |

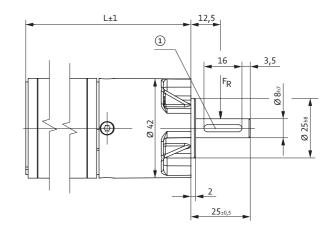
Preliminary data, subject to alterations

Technical drawing

Image of 1-stage gearhead

All dimensions in mm





- ① Fitted key / DIN 6885 A-3x3x16
- 2 4 x M3, 8 deep
- 3 4 x M4, 8 deep



Permissible shaft load

At rated speed, operating factor CB=1 and a service life expectancy L10 from 5 000 h (at TU max. 40°C in rated 150 N 250 N

Length of the possible motor / gearhead combinations

All dimensions in mm

| lotor / gearhead | | | Length L | Length L |
|----------------------|---------|-----------------|--------------------|--------------------|
| | Voltage | Reduction ratio | 1-stage gearhead | 2-stage gearhead |
| GGE4220BK1PP42100560 | 2/1/ | | 161 + 35.3 = 196.3 | |
| SGE4240BK1PP42100560 | 24V | 5 | 181 + 35.3 = 216.3 | |
| SGE4220DK1PP42100560 | / 0\ / | 5 | 196.3 | |
| SGE4240DK1PP42100560 | 48V | | 216.3 | |
| SGE4220BK1PP42100960 | 24V | | 196.3 | |
| SGE4240BK1PP42100960 | 24V | 9 | 216.3 | |
| SGE4220DK1PP42100960 | 48V | 9 | 196.3 | |
| SGE4240DK1PP42100960 | 48V | | 216.3 | |
| SGE4220BK1PP42203060 | 24V | | | 161 + 54.8 = 215.8 |
| SGE4240BK1PP42203060 | 24 V | 30 | | 181 + 54.8 = 235.8 |
| SGE4220DK1PP42203060 | 48V | 30 | | 215.8 |
| SGE4240DK1PP42203060 | 48V | | | 235.8 |
| SGE4220BK1PP42205460 | 24V | | | 215.8 |
| SGE4240BK1PP42205460 | 24V | 54 | | 235.8 |
| SGE4220DK1PP42205460 | 48V | 54 | | 215.8 |
| SGE4240DK1PP42205460 | 48V | | | 235.8 |

Preliminary data, subject to alterations

ebmpapst

www.ebmpapst.com/eci-motorer

Description

- High torques thanks to large gearing width in the first gear stage
- Good shock resistance due to housing made of case-hardened steel with linear tooth profile in the output stage
- Very quiet running due to helical teeth in the first gear stage
- Planetary wheels made of plastic with optimized sliding properties in the first stage ensure smooth operation
- Large effective diameter thanks to radial
- Arbitrary installation position permitted
- Maintenance-free grease lubrication for life

| Туре | | Performax | ®Plus 63.1 | Performax | ®Plus 63.2 |
|---|-----|-----------|------------|-----------|------------|
| Reduction ratio | | 5.00 | 9.00 | 30.0 | 54.0 |
| No. of stages | | 1 | 1 | 2 | 2 |
| Efficiency | | 0.90 | 0.90 | 0.81 | 0.81 |
| Max. input speed (n ₁) | rpm | 6 000 | 6 000 | 6 000 | 6 000 |
| Rated output torque (M _{ab}) | Nm | 11.9 | 7.60 | 64.0 | 41.0 |
| Short-term torque (M _{max}) | Nm | 29.8 | 19.0 | 160 | 102.5 |
| Gear play | 0 | 0.7 1.2 | 0.7 1.2 | 0.7 1.2 | 0.7 1.2 |
| Permissible ambient temperature range (T_U) | °C | 0 +40 | 0 +40 | 0 +40 | 0 +40 |
| Operating mode | | S1 | S1 | S1 | S1 |
| Protection class | | IP 50 | IP 50 | IP 50 | IP 50 |
| Weight | kg | 0.66 | 0.66 | 1.20 | 1.20 |
| Shaft load radial / axial | Ν | 350 / 500 | 350 / 500 | 350 / 500 | 350 / 500 |
| Service life | h | 5 000 | 5 000 | 5 000 | 5 000 |

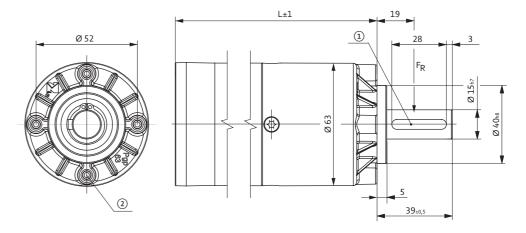
Drive Concept for SIMATIC MICRO-DRIVE · Edition 2019-04

Preliminary data, subject to alterations

Technical drawing

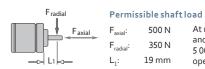
Image of 1-stage gearhead

All dimensions in mm



① Fitted key / DIN 6885 A-5x5x28

2 4 x M5, 10 deep



500 N

At rated speed, operating factor CB=1 and a service life expectancy L10 from 5 000 h (at TU max. 40°C in rated

Length of the possible motor / gearhead combinations

All dimensions in mm

| otor / gearhead | | | Length L | Length L |
|---------------------|---------|-----------------|----------------------|----------------------|
| | Voltage | Reduction ratio | 1-stage gearhead | 2-stage gearhead |
| GE6320BK1PP63100560 | 24V | | 135.6 + 57.8 = 192.8 | |
| GE6340BK1PP63100560 | 24V | | 155.6 + 57.8 = 213.4 | |
| GE6320DK1PP63100560 | | 5 | 192.8 | |
| GE6340DK1PP63100560 | 48V | | 213.4 | |
| GE6360DK1PP63100560 | | | 175.6 + 57.8 = 233.4 | |
| GE6320BK1PP63100960 | 24V | | 192.8 | |
| GE6340BK1PP63100960 | 24V | | 213.4 | |
| GE6320DK1PP63100960 | | 9 | 192.8 | |
| GE6340DK1PP63100960 | 48V | | 213.4 | |
| GE6360DK1PP63100960 | | | 233.4 | |
| GE6320BK1PP63203060 | 24V | | | 135.6 +79.2 = 214.8 |
| GE6340BK1PP63203060 | Z4V | | | 155.6 + 79.2 = 234.8 |
| GE6320DK1PP63203060 | | 30 | | 214.8 |
| GE6340DK1PP63203060 | 48V | | | 234.8 |
| GE6360DK1PP63203060 | | | | 175.6 + 79.2 = 254.8 |
| GE6320BK1PP63205460 | 24V | | | 214.8 |
| GE6340BK1PP63205460 | 24V | | | 234.8 |
| GE6320DK1PP63205460 | | 54 | | 214.8 |
| GE6340DK1PP63205460 | 48V | | | 234.8 |
| GE6360DK1PP63205460 | | | | 254.8 |

Preliminary data, subject to alterations



Description

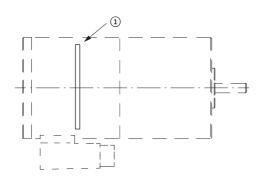
- Magnetic incremental encoder
- Motor data saved in the HSP motor library (TIA Portal; Siemens)
- Automatic component identification during assembly and start-up
- System diagnostics
- Quick and easy commissioning
- Recording and evaluation of the motor temperature (temperature model)
- Patented data transfer via available signalling lines

| Туре | iQ-Encoder (magnetic incremental encoder) | | |
|---|---|--|--|
| Output signals | 2 Square wave signals (A,B), 2 Square wave signals inverse (nA, nB) Output differential or single ended TTL compatible, phase-shifted | | |
| Number of pulses per rotation | 100 (default), other resolutions available on request | | |
| Cut-off frequency | The maximum frequency is 5 KHz | | |
| Supply voltage | + 5V (+/- 10%) (provided by SIEMENS PDCxxx=) | | |
| Power consumption | typ. 40 mA max. 100 mA | | |
| permissible output current | max. 20 mA | | |
| permissible deviation of pulse width from electrical 180° | +/- 90° | | |
| Phase shift between channel A and B | typ. 90° (+/- 30°) | | |
| Output voltage (low level) | typ. 0.25 V, max 0.8 V (I=20 mA at 5 V) | | |
| Output voltage (high level) | typ. 4.25 V, max 3.8 V (I=-20 mA at 5 V) | | |
| permissible ambient temperature range (T _U) | 0+40 | | |
| Reverse polarity protection | Takes place via short circuit of the supply voltage per protection diode, max. 200 mA continuous current permissible | | |

Preliminary data, subject to alterations

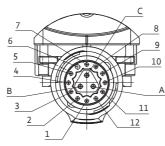
Technical drawing

All dimensions in mm



1 iQ-Encoder

Electrical connection



| | Pin | Configuration | Function |
|----------|-----|---------------|----------------------------|
| | 7 | Α | Encoder channel A |
| | 8 | /A | Encoder channel A inverted |
| Encoder | 9 | В | Encoder channel B |
| Elicodel | 10 | /B | Encoder channel B inverted |
| | 11 | +5V | Supply voltage |
| | 12 | GND | Ground |
| | | | |



Description

- Spring-applied braking
- Single-disk brakes with 2 friction contact surfaces
- Braking torque effective in powerless state
- Braking force is eliminated by electromagnetic force
- Holding brake with emergency stop function
- Currentless-operated brake with high power density
- Reduced inertia for optimum dynamics

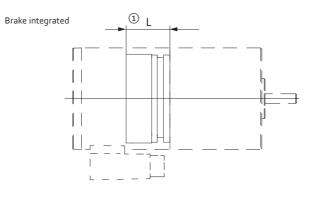
| Туре | | integrated RFK 0.3 Nm ECI-42 Brake module ECI 42-K4 | integrated RFK 1.0 Nm ECI-63 Brake module ECI 63-K4 |
|------------------------------|------|--|--|
| Nominal voltage | V DC | 24 | 24 |
| Nominal power | W | 5.0 | 9.0 |
| Braking torque | Nm | 0.12 | 1.00 |
| Closing time, actuation time | ms | 25.0 | 20.0 |
| Opening time, fall time | ms | 85.0 | 60.0 |
| | | | |

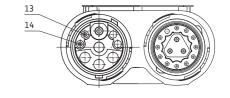
Preliminary data, subject to alterations

Technical drawing

All dimensions in mm

Electrical connection





 $\ensuremath{\ensuremath{\mathfrak{D}}}$ The drive enclosure is made longer by installation of the brake module

| Туре | L |
|-----------|-------------|
| ECI-42.20 | 113.8 ± 0.4 |
| ECI-42.40 | 133.8 ± 0.4 |
| ECI-63.20 | 155.4 ± 0.4 |
| ECI-63.40 | 175.4 ± 0.4 |
| ECI-63.60 | 195.4 ± 0.4 |
| | |

| | Pin | Configuration | Function |
|-------|-----|---------------|----------------|
| Brake | 13 | +24 V | Supply voltage |
| DIAKE | 14 | GND | Ground |

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ebm-papst St. Georgen GmbH & Co. KG Hauptverwaltung

Hermann-Papst-Straße 1 78112 St. Georgen GERMANY Phone +49 7724 81-0 Fax +49 7724 81-1309 info2@de.ebmpapst.com ebm-papst St. Georgen GmbH & Co. KG Werk 7 Lauf

Industriestraße 9
91207 Lauf a. d. Pegnitz
GERMANY
Phone +49 9123 945-0
Fax +49 9123 945-145
info4@de.ebmpapst.com